



# Review of Soft Torque Songa Venus RIG Preliminary results



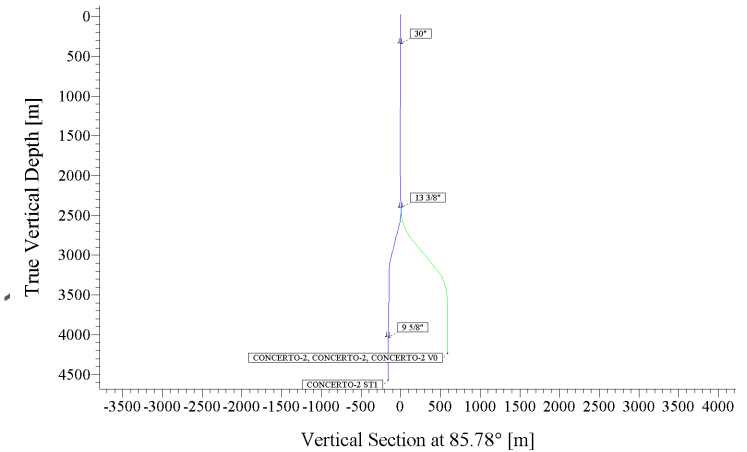
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## Situation summary

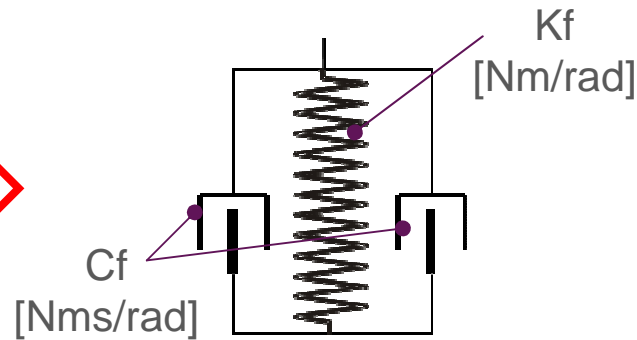
- Semi Sub Songa Venus
  - Tesco 1350ECI TD; MD5000 VFD
  - Top drive inertia: 720 kgm<sup>2</sup>.
  - Passive heave compensator (Rucker model 187)
  - Water depth~260m
- 8 ½” hole;
- 8 ½” PDC bit



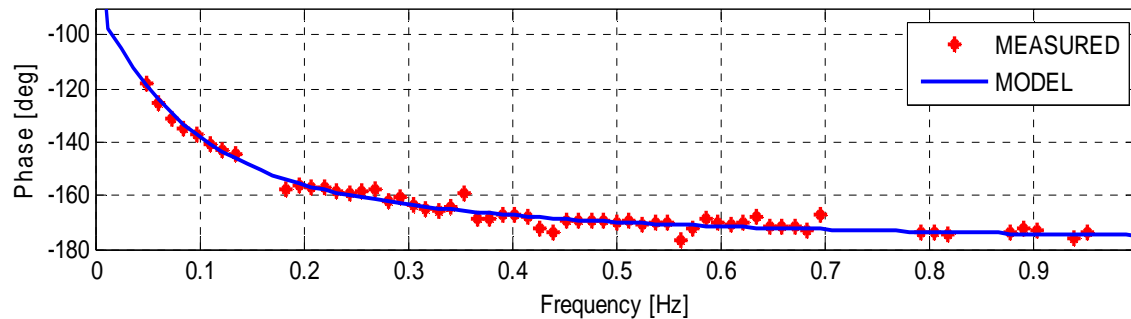
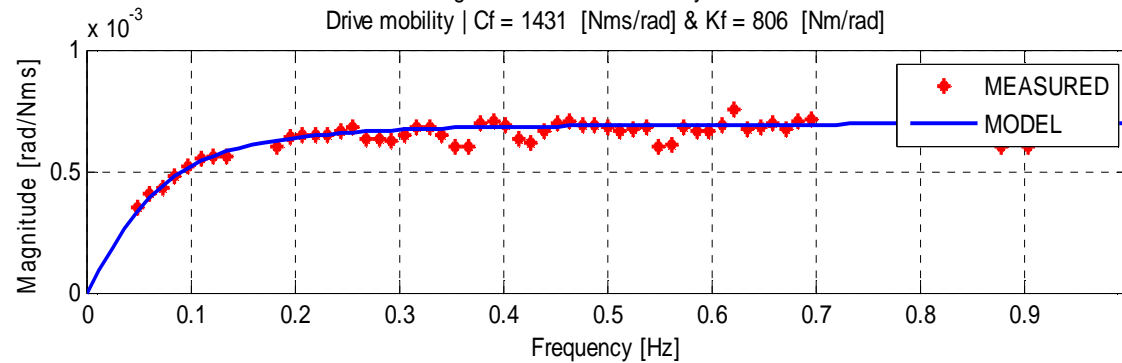
## Situation summary (2)

- STRS was installed on Friday 23/7. Several ON/OFF tests and has been working since.
  
- On Sunday 25/7 BHA #15 was pulled
  - RIH with BHA #5, drilling 8 ½” hole.
- From there on two coring runs:
  - BHA#6 (RIH on Wednesday 28/7)
  - BHA 7 (RIH on Friday 30/7)
  
- Several hours of EP’s high frequency data (200Hz- STQ and SRPM). Available between Friday 23/7 to Friday 30/7. That data is most important input to this presentation.

# STRS installation



Songa Venus EP STRS - July 23 18:12  
Drive mobility |  $C_f = 1431$  [Nms/rad] &  $K_f = 806$  [Nm/rad]



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Up to two lines if required

- STRS was installed and tested on 23/7

- STRS makes the TD behave like a tuned spring-damper.

- This means there now should be a known relation between TQ load on SRPM

- The measured drive mobility is an exact match with model.

- This proves STRS is successfully

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# STRS tuning by RTOC

Bit Depth [ m ]	Stiffness (kf) [ N-m/rad ]	Damping (cf) [ N-m-s/rad ]
4100.0	789.7	1549.5
4128.5	780.6	1545.4
4157.0	771.7	1541.3
4185.5	763.0	1537.3
4214.0	754.4	1533.3
4242.5	745.9	1529.3
4271.0	737.6	1525.4
4299.5	729.4	1521.5

•RTOC is providing Cf and Kf tuning tables using IDM 3.17

•Tuning and usage is being checked by RTOC via WITS

**String Sections (from the bottom to surface)**

Type	Pipe OD [in]	Nominal Weight [lb/ft]	Grade	Pipe ID [in]	Length [m]	Depth Base [m]
1 BIT					0.30	4,800.0
2 DC	6.75			4.2000	4.11	4,793.7
3 OTHER	6.75			2.8130	0.80	4,795.6
4 STAB	6.75			2.25	1.50	4,794.8
5 MWD	6.75			1.9200	25.11	4,793.3
6 STAB	6.75			2.25	1.76	4,788.2
7 OTHER	6.5			2.8150	1.09	4,786.4
8 OTHER	6.5			2.8130	1.22	4,785.3
9 DC	6.75			2.8100	82.29	4,764.1
10 X0	6.75		G	2.5	0.90	4,681.8
11 HwDP	5.5			3.25	180.36	4,680.9
12 JAR	7.000			3.2500	10.19	4,600.6
13 HwDP	5.5			3.25	67.80	4,490.4
14 ACC	7.000			2.8130	10.01	4,422.6
15 HwDP	5.5			3.25	18.72	4,412.6
16 DP	5.5	21.9	S	4.7780	4,289.00	4,393.8
17						

**Soft Torque Rotary System Parameters**

Tuning Criteria: Max Min Damping

Bit Depth [ m ]	Stiffness (kf) [ N-m/rad ]	Damping (cf) [ N-m-s/rad ]
1 4100	789.7	1542
2 4128.5	760.3	1537.9
3 4157	751.7	1533.8
4 4185.5	743.2	1529.9
5 4214	735	1525.9
6 4242.5	726.8	1522
7 4271	718.8	1518.1
8 4299.5	711	1514.3
9 4328	703.3	1510.5
10 4356.5	695.7	1506.7
11 4385	688.3	1503
12 4413.5	680.9	1499.3
13 4442	673.7	1495.7
14 4470.5	666.7	1492
15 4499	659.7	1488.5
16 4527.5	652.9	1484.9
17 4556	646.1	1481.4
18 4584.5	639.5	1477.9
19 4613	633	1474.5
20 4641.5	626.6	1471.1
21 4670	620.3	1467.7
22 4698.5	614.1	1464.3
23 4727	608	1461
24 4755.5	602	1457.7
25 4784	596.1	1454.5

Record ID: 50 STRS Channel: 1

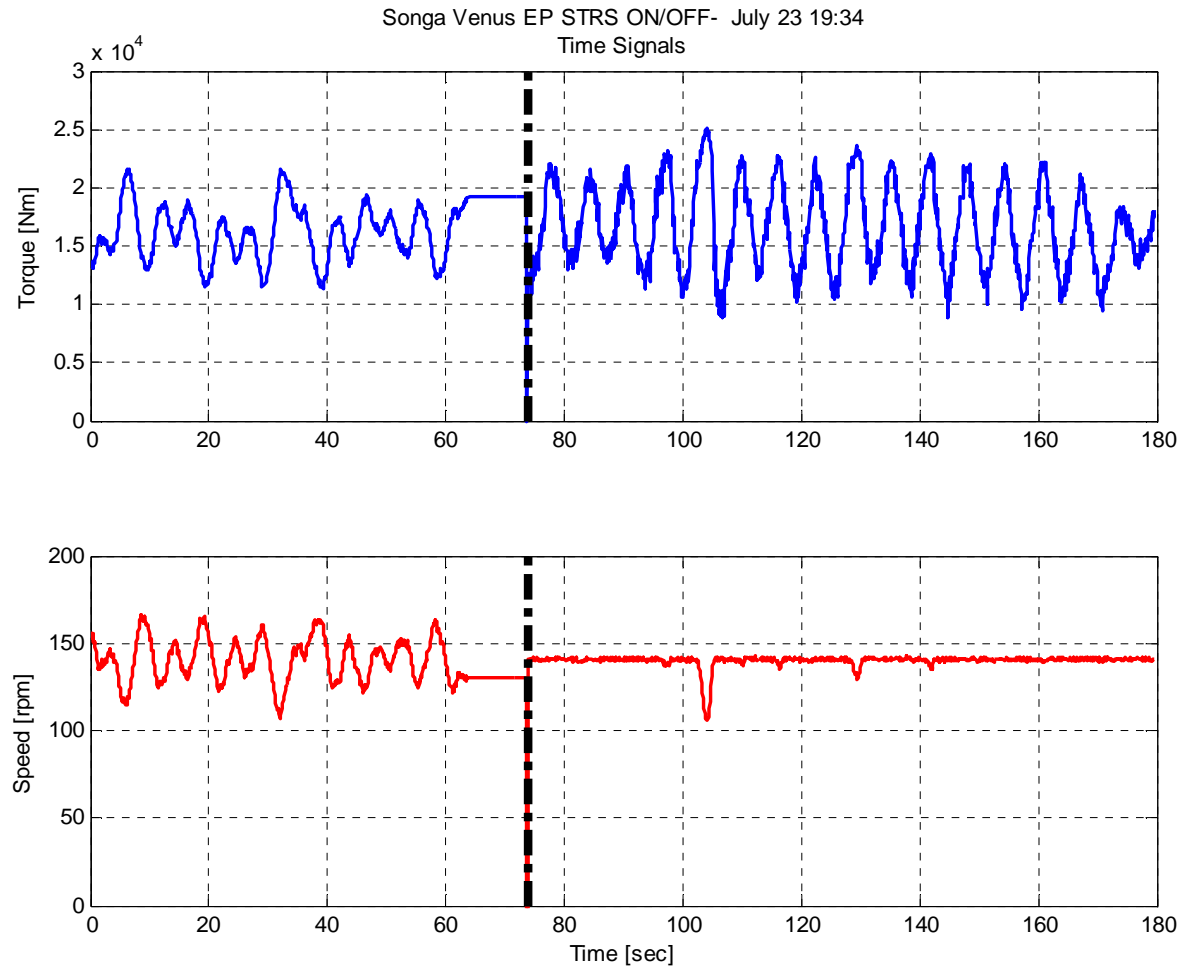
Variable	Value	Unit
04 Sequence Identifier	256597	
05 Date	100728	
06 Time	001912	
08 Torque Avg	1235.64	KFLB
09 Torque Max	3396.60	KFLB
10 Torque Min	0.00	KFLB
11 Rotary Speed Setting	0.00	RPM
12 Rotary Speed Actual	-21.65	RPM
13 STRS On/Off Status	0	
14 STRS Mode	0	
17 Top Drive Gear Ratio	18.610	
18 Top Drive Inertia	750.00	LBF2
22 STRS Kf	660.13	FLBR
23 STRS Cf	1338.55	FLSR

PRTSN: 0 Sequence #: 256597 Time: 00:19:12 Depth: 0.00

Real Time Refresh Done Help

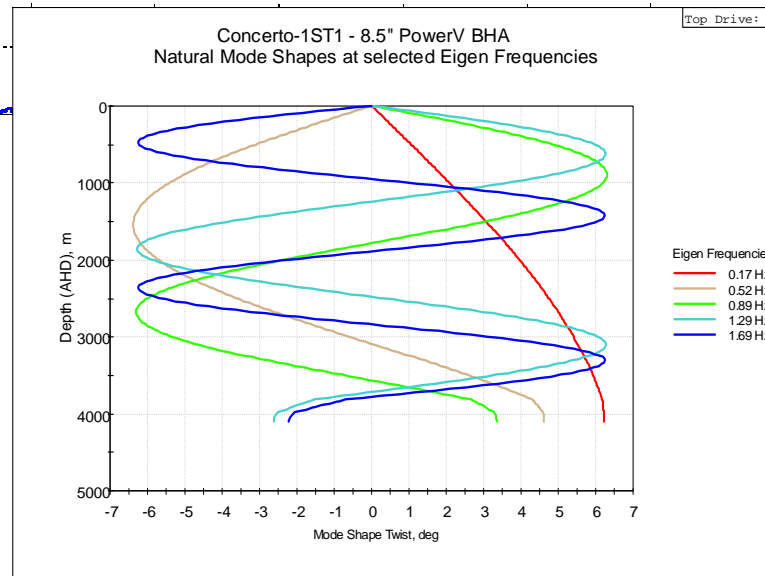
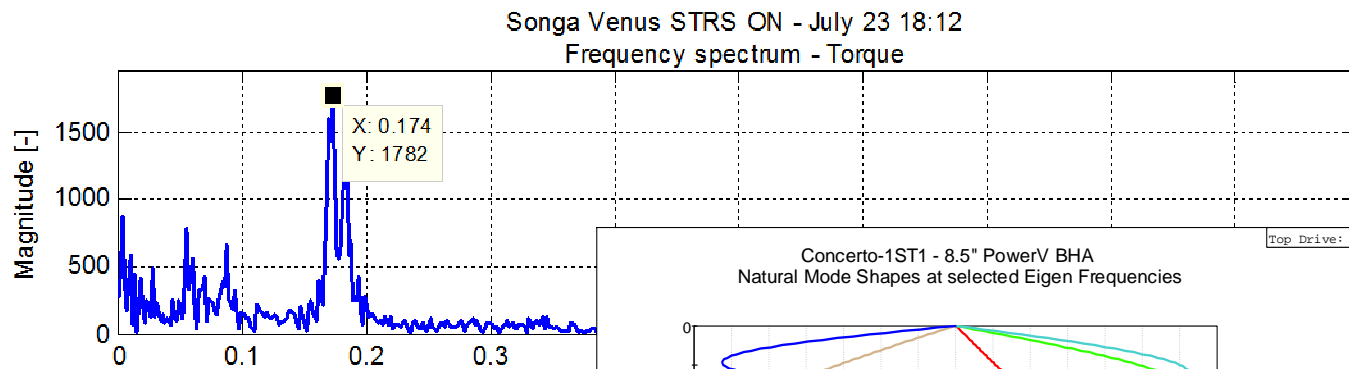
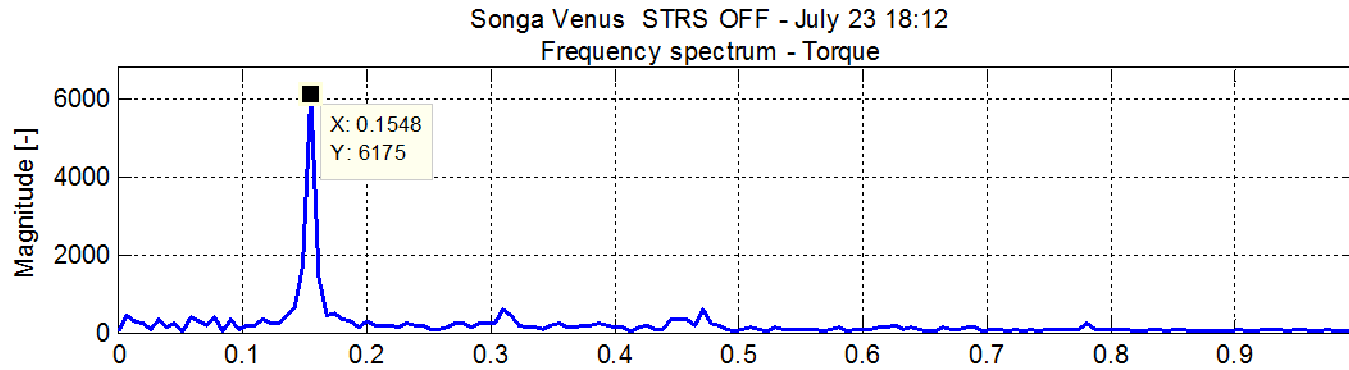


# STRS performance (1)



- First ON / OFF plot
- Showing STRS eliminating stick-slip but not eradicating
- Stick-slip starts up again after switching STRS OFF @ ~75sec.

# STRS performance (3) – Severe stick-slip



- Frequency content of surface torque for time signals on previous slide

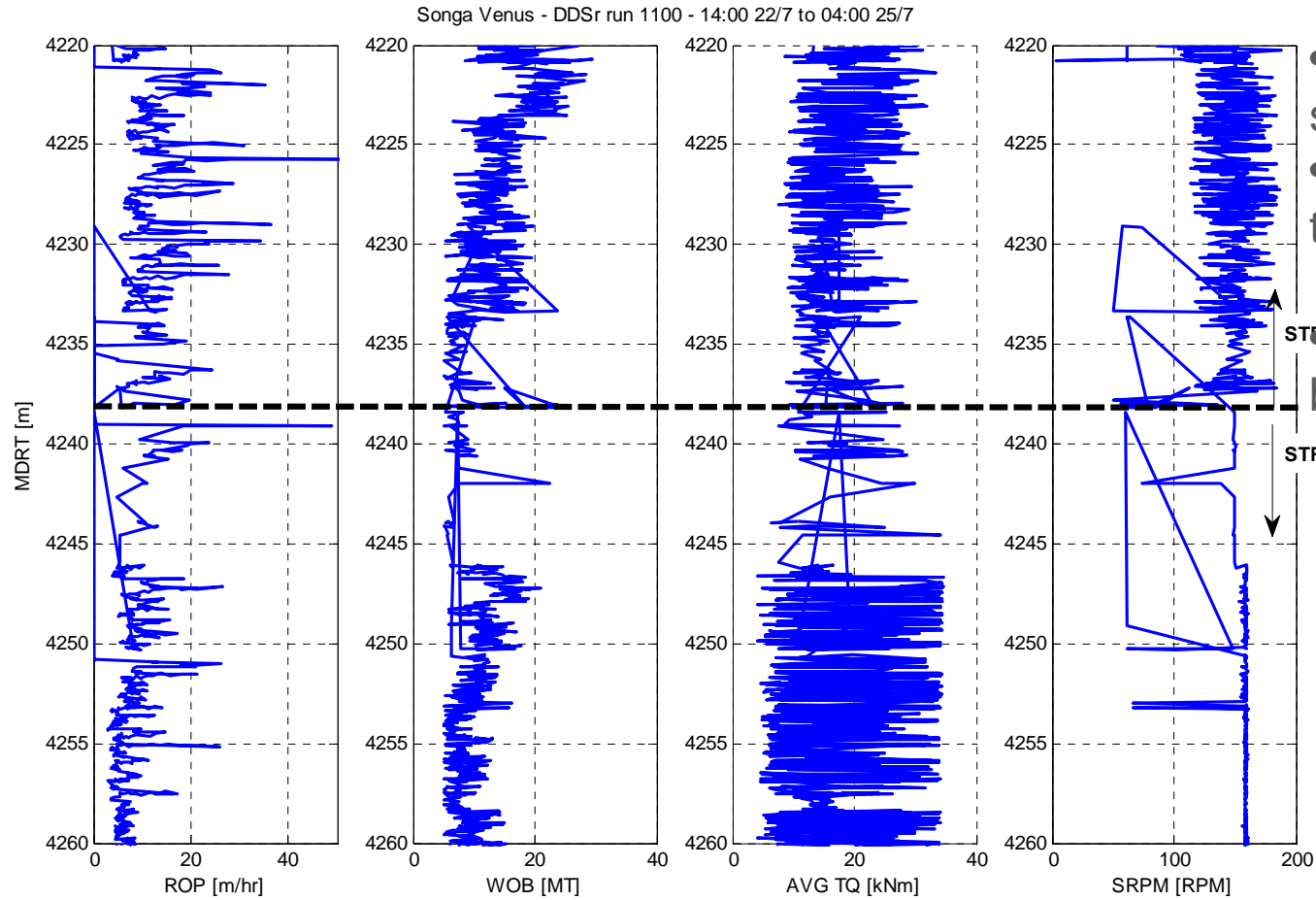
- STRS ON and OFF

- For ON, low amplitude; matching 1<sup>st</sup> torsional mode

- For OFF, high amplitude; frequency below 1<sup>st</sup> torsional mode == stick-slip



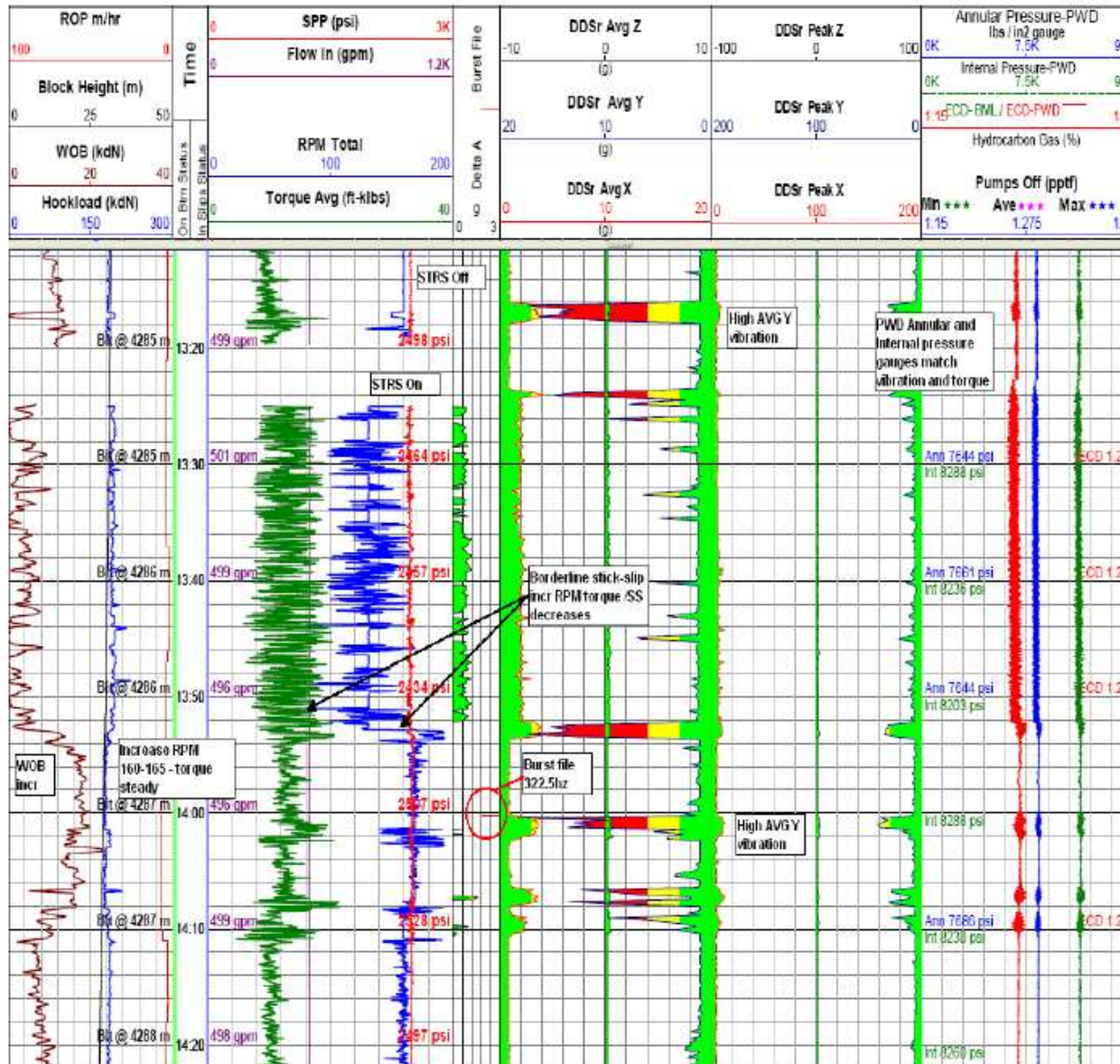
# STRS Performance (4)



- STRS reducing stick-slip
- No full eradication though

• Clear difference between ON & OFF

# Observations (1) Effect of rotary speed



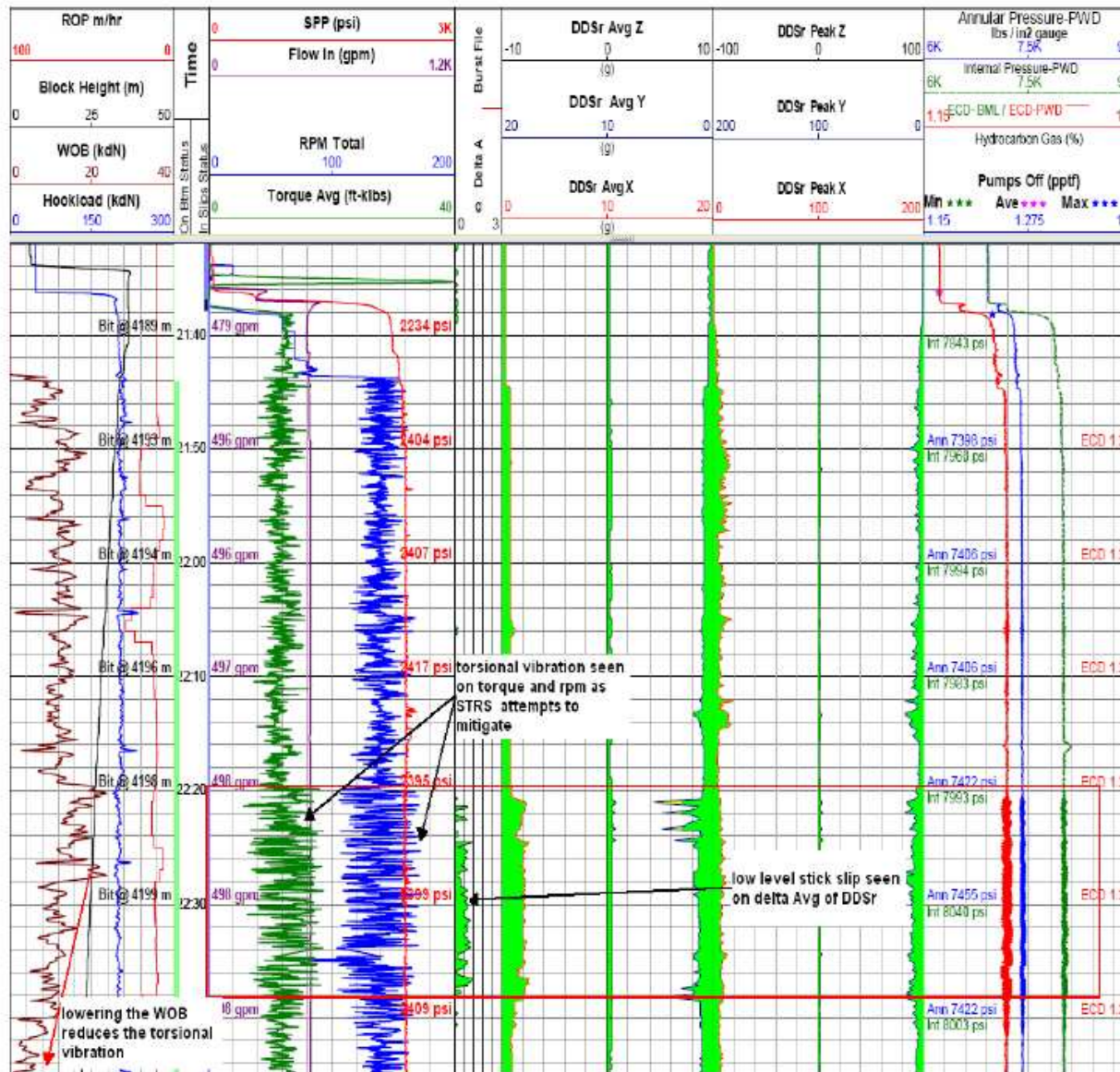
The plot opposite displays when the STRS was again switched on towards the end of the run. Initially with the RPM at 135 RPM the torque signal is very cyclic and the DDSr is recording low/moderate stick slip. The variations seen in the RPM indicate that the STRS is attempting to reduce the amount of cyclic torque but the conditions for stick slip are borderline.

Increasing the RPM to 160-165 RPM results in the STRS being able to effectively reduce the cyclic nature of the torque. The downhole PWD pressure gauges are also smoother as the STRS reduces the downhole torsional vibration. The DDSr Delta Avg reduces to zero in response to the increase in RPM.

There are several short incidents of high Avg Y vibration and the STRS appears to respond to this.

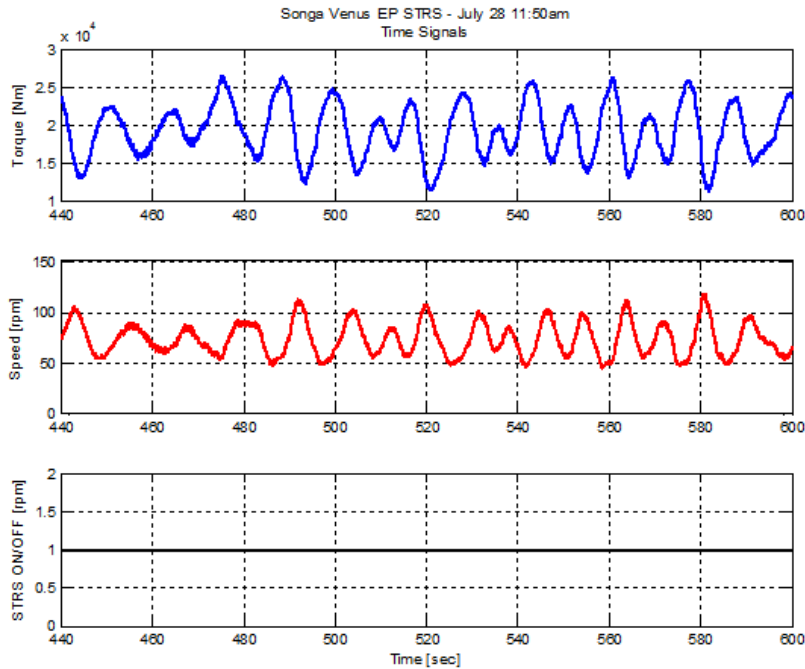
(24-07-10 at 13:20 Hrs – 4285m)

# Observations (2) Stick slip and weight-on bit

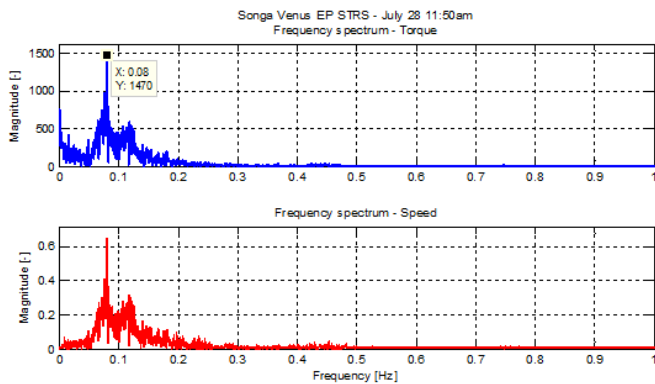


- Soft Torque suppresses but not fully eliminates the stick-slip
- Increasing the WOB increases the stick slip level
- Suggests bit generated stick slip
- Confirms earlier studies that linked stick slip to the bit drilling the harder formations (sands, volcanics)

# Observations (3) "Heave induced stick-slip"

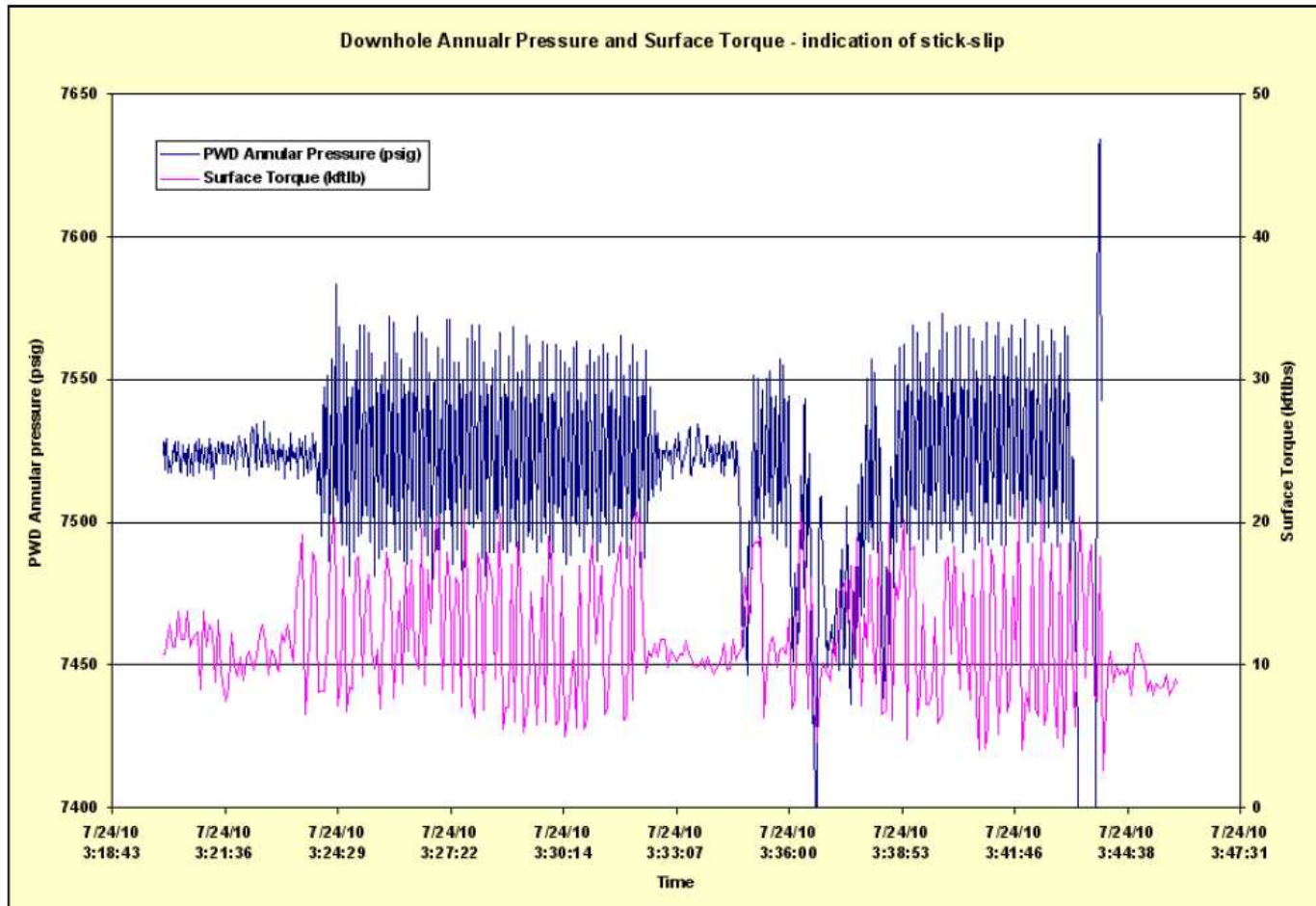


- On several occasions STRS eliminates stick-slip, but heave-induced vib's remain
- Amplitude TQ variation >10kNm (!)
- Frequency of this oscillation is ~0.08Hz. (as compared with ~ 0.17 Hz from stick slip)
- Confirmed to match ocean swell from that day.
- STRS cannot cure this!



Date:	28-Jul-10	Location:	Concerto 2 ST1										
Rig Heading:		110°											
Latitude:		13°40' S											
Longitude:		123°21.5' E											
Water Depth:		879											
Bulk Data													
	Rig Fuel	Drill Water	Pot Water	Brine	Base Oil	SBM	WBM	Ort Neat G	Ort Blend HTB	Barite	Benton	Heli fuel	Avail Deck Load
	M3	M3	M3	M3	M3	M3	M3	MT	MT	MT	MT	LTS	LT
Yesterday	582	1438	103	143	95	228	0	16	71	78	36	12112	691
Rec	0	0	89	0	0	46	0	0	0	0	0	0	N/A
Used	20	14	34	0	0	38	0	0	0	0	0	865	N/A
Today	562	1424	158	143	95	236	0	16	71	78	36	11247	674
Weather													
Wind						Wave							
Wind speed (kts)	10					Period (sec)	3						
Wind direction	SE					Direction	ESE						
10	15					Height (m)	2						
Swell													
Current speed (kts)	N/A					Period (sec)	13						
Current direction (deg)	N/A					Height (ft)	2						
Temperature (deg C) HL	34				24	Heave (m)	0.5						
Visibility (naut miles)	9					Pitch (deg)	0.3						
Cloud cover	3/8					Roll (deg)	0.5						
Barometric pressure (mbar)	1016												

## Observations (4) Coupling between PWD and Stick Slip



Note: Small shift in time data

- Stick slip couples with internal and external PWD sensor
- Seen this before in the NAM 15 years ago
- Suspect that varying rotational speeds causes varying pressure drops
- Not fully understood

## Conclusions

- Severe stick slip observed during 8.5" run
  - With no STRS upto 15kNm amplitude!
- Soft Torque
  - STRS successfully installed
  - STRS effective most of time in surpressing stick-slip
  - For severe stick-slip STRS sometimes not able to fully eradicate
  - **Using low WOBs and High RPMs will give the best results**
  - Tuning via Miri RTOC works